Phantom[®] Premium[™]

Advanced haptic devices for academic and commercial research and development

The 3D Systems Phantom[®] Premium[™] haptic devices fulfill the requirements of a vast range of research and commercial applications. These high-precision devices provide the largest workspaces and highest forces in the Phantom line while offering a broad range of force feedback workspaces, various ranges of motion and varying stiffness. Phantom Premium haptic devices also come in 6DOF models, which offer 6 degrees of freedom (3 translational, 3 torque) in output capabilities suitable for virtual prototyping, maintenance path planning and molecular modeling applications.

With ranges of motion approximating hand movement pivoting at the wrist, elbow or shoulder, the Phantom Premium can fulfill the requirements of manufacturing verification, machine component visualization, medical research and simulation, and an assortment of other haptically-enabled 3D applications.

While the models are designed with different ranges of motion and specifications, each one is constructed for maximum durability and simple PC connection via the parallel port (EPP) interface. A wide variety of end-effector devices enable options including thimble gimbals, finger sleds, pinch functionality and more.

The Open Haptics Toolkit available with these devices delivers a comprehensive software library to enable rapid development of applications using force-feedback.



Phantom[®] Premium[™]

Translational

Rotational

Translational

Rotational

Yaw & Pitch

Translational

Rotational

Yaw & Pitch

Yaw

Pitch

Roll

Roll

Roll

Advanced haptic devices for academic and commercial research and development

Phantom Premium 6D0Fs Specifications

Workspace

Range of motion

Nominal position

exertable force and

torque at nominal

. (orthogonal arms)

Force feedback

(6 Degrees of Freedom) Position sensing/input

(6 Degrees of Freedom)

Optional end effectors

resolution

Maximum

position

Stiffness

Interface



Premium 1.5 High Force / 6DOF

15 W x 10.5 H x 7.5 D in

381 W x 267 H x 191 D mm

297 degrees / 5.18 radians

260 degrees / 4.54 radians

335 degrees / 5.85 radians

Lower arm movement pivoting

at elbow

3784 dpi / 0.007 mm

0.0023 degrees/0.00004 radians

0.0080 degrees/0.00014 radians

8.4 lbf / 37.5 N

73 oz-in / 515 mNm

24 oz-in / 170 mNm

20 lbf in-1 / 3.5 N mm-1

x, y, z, Tx, Ty, Tz

x, y, z, roll, pitch, yaw

Parallel port

Thumb pad (pinch), scissors



Premium 3.0 / 6DOF

33 W x 23 H x 16 D in 838 W x 584 H x 406 D mm

297 degrees / 5.18 radians 260 degrees / 4.54 radians 335 degrees / 5.85 radians

Full arm movement pivoting at shoulder

> 1000 dpi / ~0.02 mm

0.0023 degrees/0.00004 radians 0.0080 degrees/0.00014 radians

4.9 lbf / 22N

73 oz-in / 515 mNm 24 oz-in / 170 mNm

5.7 lbf in-1 / 1 N mm-1

x, y, z, Tx, Ty, Tz

x, y, z, roll, pitch, yaw

Parallel port

Thumb pad (pinch), scissors

Contact Information

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APAC

Premium 1.5 / 6DOF

15 W x 10.5 H x 7.5 D in

381 W x 267 H x 191 D mm

297 degrees / 5.18 radians

260 degrees / 4.54 radians

335 degrees / 5.85 radians

Lower arm movement pivoting

at elbow

860 dpi / 0.03mm

0.0023 degrees/0.00004 radians

0.0080 degrees/0.00014 radians

1.9 lbf / 8.5 N

73 oz-in / 515 mNm

24 oz-in / 170 mNm

20 lbf in-1 / 3.5 N mm-1

x, y, z, Tx, Ty, Tz

x, y, z, roll, pitch, yaw

Parallel port

Thumb pad (pinch), scissors

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3D SYSTEMS

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